

* * Lecture: ①

Example: 3 ϕ , 5 kVA, 208 V, 4p, 60 Hz

Y connection, $X_s = 8 \Omega$, 0.8 p.f lag.

② - Determine the excitation voltage & power angle?

$$\Rightarrow V_p = \frac{208}{\sqrt{3}} = 120 \text{ V/phase.}$$

$$\Rightarrow I_{\text{rated}} = \frac{5000}{\sqrt{3} \times 208} = 13.9 \text{ A.} \Rightarrow \theta = \cos^{-1}(0.8) = -37^\circ (\text{lag}).$$

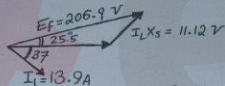
$$\Rightarrow E_f = V_t + I_L Z_s = 120 + (13.9 (0.8 - j0.6) * (j8))$$

$$E_f = 206.9 \angle 25.5^\circ$$

$$\therefore \text{power angle} = 25.5^\circ = \delta$$

$$\text{OR: } + I_L X_s + 13.9 \angle -37^\circ \times 8 \angle 90^\circ$$

Phasor
Diagram



⑥ - If the field excitation current increased by 20% without changing the power, find stator current, power factor, Reactive kVA?

$$I_{f2} = 1.2 I_{f1}$$

$$E_{f1} \sin \delta_1 = E_{f2} \sin \delta_2 \quad (\text{Because Power = constant})$$

$$\text{But } E_{f2} = 1.2 E_{f1} \quad (E_f \propto I_f)$$

$$= 248.28 \text{ V}$$

$$\therefore \sin(\delta_2) = \frac{E_{f1} \sin(\delta_1)}{E_{f2}} = \frac{\sin(25.5)}{1.2} = 0.359$$

$$\Rightarrow \delta_2 = \sin^{-1}(0.359) = 21^\circ$$

$$\Rightarrow I_{L2} = \frac{E_{f2} - V_t}{jX_s} = \frac{248.28 \angle 21^\circ - 120}{j8} = 17.86 \angle -51.5^\circ$$

$$\Rightarrow \text{p.f} = \cos(-51.5) = 0.623 \text{ lagging.}$$

$$\text{Reactive Power} \Rightarrow Q = 3 V I \sin \theta$$

$$= 3 (120) (17.86) \sin(51.5) = 5031 \text{ VAR}$$

$$= 5.031 \text{ kVAR.}$$

$$\& Q_1 = 3 (120) (13.9) \sin(37) = 3.011 \text{ kVAR}$$

keeping I_f constant ($E_f = \text{constant}$), what's the max. power, stator current, p.f, Q (Reactive Power).

$$I_f = \text{constant} \Rightarrow E_f = \text{constant}$$

∴ max power @ $\delta = 90^\circ$

$$\Rightarrow P_{\max} = \frac{3V_T E_f \sin \delta}{X_s} = \frac{3(120)(206.9) \sin 90}{j8} = 9310 \text{ W}$$

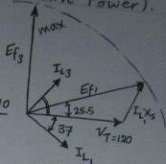
$$\Rightarrow I_{L3} = \frac{j206.9 - 120}{j8} = 29.9 \angle 30.1^\circ$$

$$\Rightarrow \text{p.f} = \cos(30.1) = 0.865 \text{ leading.}$$

$$\Rightarrow Q_3 = 3(120)(29.9) \sin(30.1) = -5400 \text{ VAR}$$

$$Q_3 = -5.4 \text{ kVAR. (negative)}$$

• ملاحظة: دائماً الاشارة تكون عكس التيار، اذا كان الـ (-) أو (lag) تكون اشارة موجبة، والعكس صحيح.



1) keeping Torque as it was, I_f reduced by 20%?

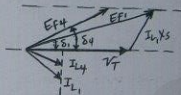
Torque = Constant $\Rightarrow$ Power is constant.

$$\Rightarrow I_{f4} = 0.8 I_{f1} \Rightarrow E_{f4} = 0.8 E_{f1} = 165.52 \text{ V}$$

$$E_f \sin \delta_1 = E_{f4} \sin \delta_4$$

$$\Rightarrow \delta_4 = \sin^{-1} \left(\frac{\sin(25.5)}{0.8} \right) = 32.5^\circ$$

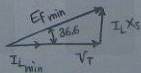
$$\Rightarrow I_{L4} = \frac{165.52 \angle 32.5 - 120}{j8} = 11.4 \angle -12.4^\circ$$



$$\text{Find } I_{\min} ? I_{L_{\min}} = I_{L1} \cos \theta_1 = 13.9 \cos(37) = 11.13 \text{ A}$$

$$\underline{OR} = I_{L4} \cos \theta_4 = 11.4 \cos(12.4) = 11.13 \text{ A}$$

$$\Rightarrow E_{f_{\min}} = 120 + 11.13 \angle 0 * j8 = 149.43 \angle 36.6^\circ \text{ V}$$



keeping I_f as it was, increasing Torque by 25%.

$$T_5 = 1.25 T_1 \Rightarrow P_5 = 1.25 P_1 \text{ (power increased)}$$

$$\text{But } \Rightarrow E_f = \text{constant} \Rightarrow \text{power angle increased.}$$

$$P_5 = 1.25 P_1$$

$$E_f \sin \delta_5 = 1.25 (E_f \sin \delta_1)$$

$$\Rightarrow \delta_5 = \sin^{-1}(1.25 \sin(25.5^\circ))$$

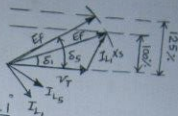
$$= 32.5^\circ$$

$$\Rightarrow I_{L5} = \frac{206.9 / 32.5 - 120}{j8} = 15.5 / -26.1^\circ$$

$$P_1 = 3(120)(13.9) \cos(36.8^\circ) = 4 \text{ kW}$$

$$\Rightarrow P_5 = 3(120)(15.5) \cos(26.1^\circ) = 5 \text{ kW} = (125\% P_1)$$

$$\Rightarrow Q_5 = 3(120)(15.5) \sin(26.1^\circ) = 2.45 \text{ kVAR}$$



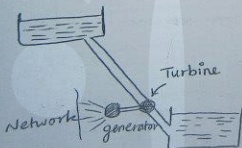
* * Lecture 2 ...

Synchronous Motors ...

it's not a synchronous motor unless it's working on $n_s = \frac{120 f}{P}$; other than that it's not a synchronous motor. so the problem is how to start it from zero speed.

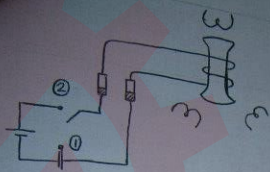
* Starting of Synchronous Motor ...

1. - By Prime Mover : starting as a synchronous generator $\Rightarrow$ Synchronization $\Rightarrow$ then it's loaded as a motor!



- Pumping Station
It works as a generator.
when we need electricity like
@ 8:00 P.M., then @ mid-night
when electricity is not needed
we pump the water back up.

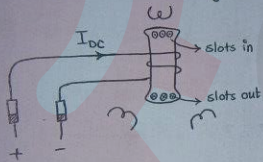
starting as induction Motor ...



- 1- start as induction motor
- 2- synchronous motor.

→ When Induction motor speed reaches like 1480, the switch ② is connected, so speed is now 1500 & it becomes as a synchronous.

3 - By Damper Winding ...



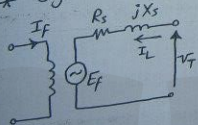
@ synchronous speed.

if loaded; speed will ↓

if load removed; speed will ↑

electrical damper will bring the speed back to n_s & also it's important @ starting.

* Synchronous Motors ...

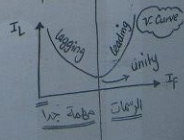
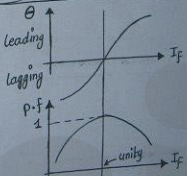
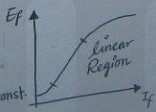
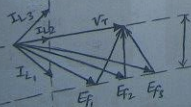
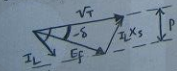


• motor

$$V_T = E_f + I_L Z_s$$

• generator

$$E_a = V_T + I_L Z_s$$



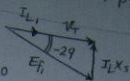
208 V, 60 Hz, $P = 3 \text{ kW}$, $X_s = 8 \Omega$, $p.f. = 1.0$, $n_s = 1800$

$$\Rightarrow I_L = \frac{3000}{\sqrt{3} \times 208} = 8.33 \text{ A}$$

$$\Rightarrow E_f = V_T - I_L X_s ; V_T = \frac{208}{\sqrt{3}} = 120$$

$$= 120 - 8.33 \angle 0^\circ \times j8$$

$$= 137.3 \angle -29^\circ$$



(b) if $I_f = \text{constant}$, load increased, find the max. torque that the motor can deliver?

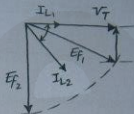
$$\Rightarrow E_f = \text{constant} \Rightarrow E_{f1} = E_{f2}$$

$$E_{f1} \sin \delta_1 = E_{f2} \sin \delta_2$$

$$\Rightarrow P_{\max} = \frac{3 \times 120 \times 137.3}{8j} = 6180 \text{ W}$$

$$\Rightarrow T = \frac{P}{\omega_s} = \frac{6180}{1800 \left(\frac{2\pi}{60} \right)} = 32.8 \text{ N-m}$$

$$\Rightarrow I_{L2} = \frac{120 + 137.3j}{j8} = 22.8 \angle -41^\circ$$



(c) If the load kept as in (a), find the current if the field current is decreased by 20%.

$$\Rightarrow E_{f3} = 0.8 E_{f1} = \frac{80}{100} (137.3) = 109.84$$

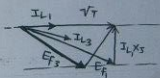
$$\Rightarrow E_{f1} \sin \delta_1 = E_{f3} \sin \delta_3 \quad (P = \text{constant})$$

$$\delta_3 = \sin^{-1} \left(\frac{\sin(-29)}{0.8} \right) = -37.3^\circ$$

$$\Rightarrow I_{L3} = \frac{120 - 109.84 \angle -37.3^\circ}{j8} = 9.27 \angle -26^\circ$$

$$\Rightarrow P = 3(120)(9.27) \cos(-26) = 3000 \text{ W}$$

$$\Rightarrow Q = 3(120)(9.27) \sin(26) = 1463 \text{ VAR}$$

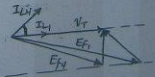


(d) same of (c); But field current increased by 20%.

$$\Rightarrow E_{f4} = 1.2 E_{f1} = 1.2 (137.3) = 164.76$$

$$\Rightarrow \delta_4 = \sin^{-1} \left(\frac{\sin(-29)}{1.2} \right) = -23.8^\circ$$

$$\Rightarrow I_{L4} = \frac{120 - 164.76 \angle -23.8^\circ}{j8} = 9.2 \angle 24.5^\circ$$



mechanical load is increased by 20%. but field current is kept as it was.

$$\Rightarrow P_5 = 1.2 P_1 = 1.2(3000) = 3600 \text{ W.}$$

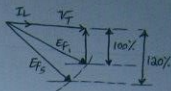
$$E_f = \text{constant} \Rightarrow E_f = E_{f5}$$

$$\Rightarrow \delta_5 = \sin^{-1} \left(\frac{1.2 \sin(-29)}{1} \right) = -35.6^\circ$$

$$\Rightarrow I_L = \frac{120 - 137.3 \angle -36^\circ}{j8} = 10.05 \angle -6^\circ$$

$$\Rightarrow P = 3(120)(10.05) \cos(-6) = 3598 \text{ W.}$$

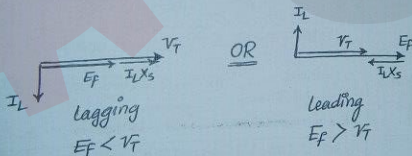
$$\Rightarrow Q = 3(120)(10.05) \sin(6) = 378 \text{ VAR.}$$



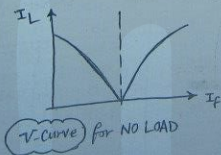
* Notes

If the power goes to zero. "Mechanical Load" = 0.

(E_f) will be in the same line as V_T . But may be higher OR lower!



$\Rightarrow$ Be Careful: Both Cases are Motors!



ecture: ③ ...

Power factor Correction using Synchronous Motors ...

Example: Industrial plant with following data:

- 1- 1000 hp induction motor, 0.85 p.f lag, 90% efficiency.
- 2- 1000 kVA induction motor, 0.8 p.f lag.
- 3- 500 kW Lighting Load, 1 p.f.
- 4- 600 kW synchronous motor.

it's required to correct overall p.f to 0.92 lag.
what's the kVA of S.M to do this job?

$$\textcircled{1} \left\{ \begin{aligned} P_{in} &= \frac{1000 \text{ hp} \times 746}{0.9} = 828.9 \text{ kW.} \\ \theta &= \cos^{-1}(0.85) = -31.8^\circ \text{ (lag).} \\ S &= \frac{P}{\text{p.f}} = \frac{828.9}{0.85} = 975.18 \text{ kVA.} \\ Q &= \sqrt{975.18^2 - 828.9^2} = 513.7 \text{ kVAR.} \end{aligned} \right.$$

$$\textcircled{2} \left\{ \begin{aligned} S &= 1000 \text{ kVA; } P = S \times \text{p.f} = 1000(0.8) = 800 \text{ kW} \\ Q &= \sqrt{1000^2 - 800^2} = 600 \text{ kVAR.} \\ \theta &= \cos^{-1}(0.8) = -36.9^\circ \text{ (lag).} \end{aligned} \right.$$

$$\textcircled{3} \left\{ \begin{aligned} P &= 500 \text{ kW, } \text{p.f} = 1 \Rightarrow \theta = 0 \\ S &= 500 \text{ kVA, } Q = 0 \end{aligned} \right.$$

LOAD	P	Q	S	p.f	θ
I.M	828.9	513.7	975.18	0.85 lag	-31.8°
I.M	800	600	1000	0.8 lag	-36.9°
L.L	500	0	500	1.00	0
S.M	600	48.8	602	0.997 lag	-4.65°
	2728.9	1162.5	2966.2	0.92 lag	-23.08
OVERALL					

* NOTES



$$\cos \theta = \text{p.f}$$

$$S^2 = P^2 + Q^2$$

$$S \times \cos \theta = P$$

$$\rightarrow S \times \text{p.f} = P$$

$$S \times \sin \theta = Q$$

$$\Sigma Q = Q_{\text{total}}$$

$$\Sigma P = P_{\text{total}}$$

$$\Sigma S \neq S_{\text{total}}$$

$$P_{\text{tot}} = 2728.9 \text{ kW}$$

$$P.f_{\text{tot}} = 0.92 \text{ lag.}$$

$$\Rightarrow S_{\text{tot}} = \frac{2728.9}{0.92} = 2966.2 \text{ kVA.}$$

$$\Rightarrow Q_{\text{tot}} = \sqrt{2966.2^2 - 2728.9^2} = 1162.5 \text{ kVAR.}$$

$$\begin{aligned} \circ \circ \quad Q_{SM} &= Q_{\text{tot}} - 513.7 - 600 \\ &= 1162.5 - 513.7 - 600 = 48.8 \text{ kVAR.} \end{aligned}$$

$$\circ \circ \quad S_{SM} = \sqrt{48.8^2 + 600^2} = 602 \text{ kVA} \#$$

$$\theta = \tan^{-1}\left(\frac{Q}{P}\right) = \tan^{-1}\left(\frac{48.8}{600}\right) = 4.65^\circ$$