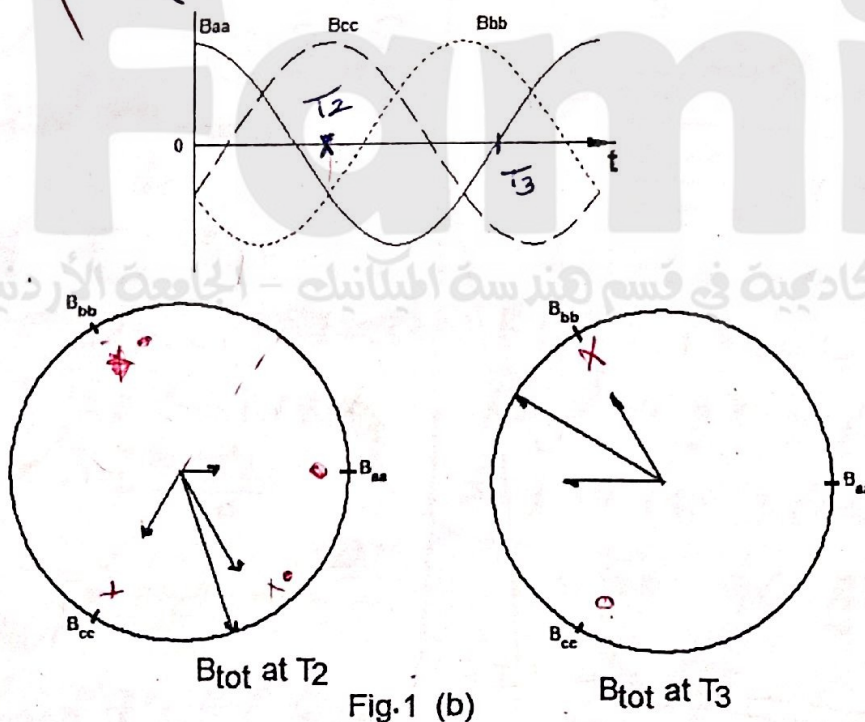
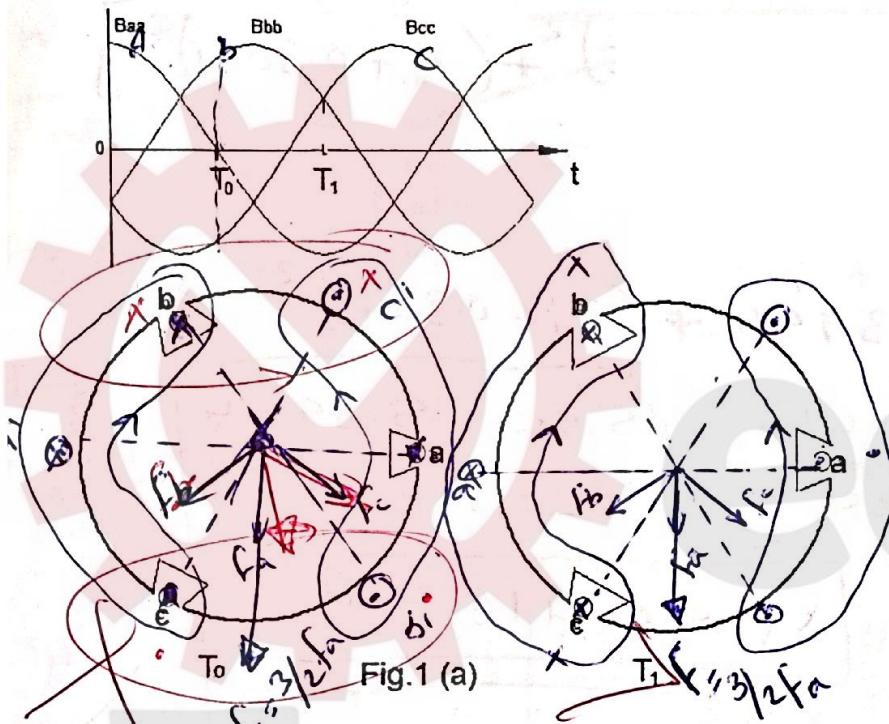


Student Name(Arabic):

Student, ID

(2-8)

Problem1 [6 marks] Use Fig.1(a) to explain the concept of rotating magnetic field and show the resultant magnetic force and location of poles at instants of time, T_0 , and T_1 . Use Fig1.(b) to determine the instants of time T_2 , and T_3 on the time domain plot of the flux density.



باقى حل السؤال 2. part 2. Q2

$$\left(\frac{V \phi}{I_1} \right)^2 = \left[(R_1 + R_f)^2 + (X_1 + X_f)^2 \right]$$

$$\left(\frac{400/\sqrt{3}}{94.96} \right)^2 = \left[(2.1726 + 0.15)^2 + (X_1 + 0.3041)^2 \right]$$

~~2.4431~~ =

$$5.914 = 5.3944 + (X_1 + 0.3041)^2$$

$$\therefore X_1 + 0.3041 = \sqrt{5.914 - 5.3944}$$

$$X_1 + 0.304 = 0.7207 \Omega$$

$$\therefore \boxed{X_1 = 0.4167 \Omega}$$

3d

P

Problem2: [8 marks] A three-phase 400 V, 50 Hz, 4-pole, Y-connected, induction motor. The torque speed curve is given in Figure (1). Neglect rotational, core, friction and windage losses except the load losses (stator and rotor). It has the following constants: $R_1 = 0.15 \Omega$, $R_2' = 0.45 \Omega$, $X_2' = j 0.21 \Omega$; $X_m = j 50 \Omega$. If the motor runs at full load speed of 1192 r.p.m. Find Line current I_A and X_1 . Note: do not assume that $X_1 = X_2$

interpolation

2.2

500

1192

0.62

50

0.3

$$n = 1192$$

$$T_{\text{induced}} = 374.2 \text{ N.m}$$

$$P_{\text{ag}} = T_{\text{ind}} \cdot \omega_{\text{syn}}$$

$$\omega_{\text{syn}}$$

$$\omega_{\text{syn}} = \frac{120f}{P}$$

$$= \frac{120(50)}{4} = 1500 \text{ rpm}$$

$$s = \frac{n_s - n_m}{n_s} = \frac{1500 - 1192}{1500} = 0.205$$

$$\omega_{\text{syn}} = \frac{2\pi n_{\text{syn}}}{60} = 157.07$$

$$P_{\text{ag}} = T_{\text{ind}} \cdot \omega_{\text{syn}} = 374.2(157.07)$$

$$= 58779.19 \text{ W}$$

$$P_{\text{ag}} = 3 I_2^2 \frac{R_2}{s}$$

$$58779.1 = 3 I_2^2 \frac{0.45}{0.205}$$

$$I_2 = 94.47 \text{ A}$$

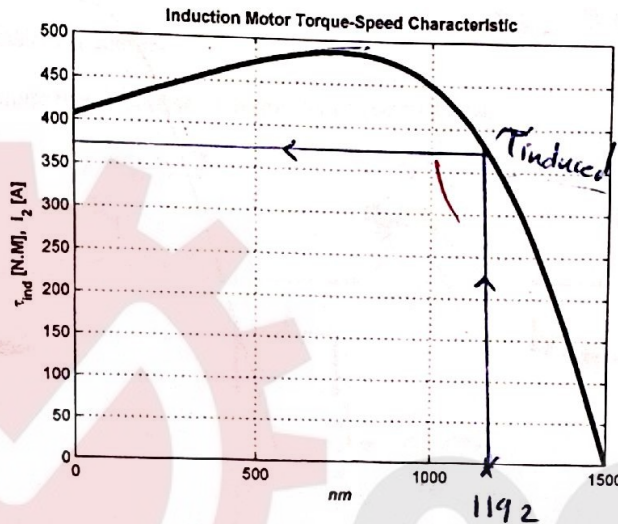


Figure 1

$$Z_f = \frac{j X_m \cdot (R_2/s + j X_2)}{\frac{R_2}{s} + j(X_m + X_2)} = R_f + j X_f$$

$$= \frac{50j(0.45/0.205 + 0.21j)}{\frac{0.45}{0.205} + (50 + 0.21j)}$$

$$= 2.1726 + 0.3041j$$

$$\therefore R_f = 2.1726 \Omega, X_f = 0.3041 \Omega$$

$$P_{\text{ag}} = 3 I_1^2 R_f$$

$$58779.19 = 3 (I_1)^2 (2.1726)$$

$$I_1 = 94.96 \text{ A} \quad \text{To check.}$$

$$I_2 = \frac{I_1 X_m}{\sqrt{(X_m + X_2)^2 + (\frac{R_2}{s})^2}} = 94.47 = I_1 (0.994)$$

$$\rightarrow I_1 = \frac{94.47}{0.994}$$

$$I_1 = 94.957 \text{ A}$$

Problem3: [7 marks] Problem1. The following test result were obtained when testing a three phase, 400-V, 50-Hz, 4 pole Y-connected, induction motor:

	V, V	I, A	P, kW	F, Hz
No-load test	400	30	4	50
Blocked-rotor test	100	100	9.6	25
Dc Test	3	10	-	0

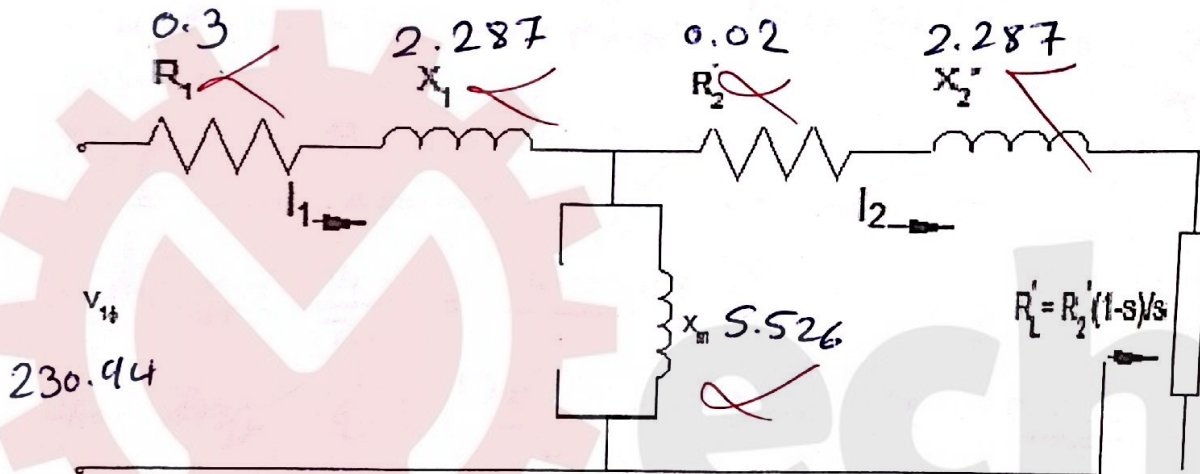
$$p = 4$$

$$f = 50 \text{ Hz}$$

$$V = 400 \text{ V} \quad V_1 = 400/\sqrt{3} = 230.94$$

1. Find the No-load rotational losses.

2. Find and write all constants calculated from tests carried out.



$$P_{rot} = P_{NL} - 3I_1^2 R_1$$

$$R_1 = \frac{V}{I} = \frac{3}{10} = 0.3 \Omega$$

$$P_{rot} = 4000 - 3(30)^2 (0.3) = 3190 \text{ W} \Rightarrow 3.19 \text{ kW}$$

$$Z_{NL} = \frac{V_1}{I_1} = \frac{230.94}{30} = 7.698 \Omega$$

$$R_{NL} = \frac{4000}{3(30)^2} = 1.481 \Omega$$

$$X_{NL} = X_1 + X_m = (Z_{NL}^2 - R_{NL}^2)^{1/2} = 7.554 \Omega$$

$$X_1 + X_m = 7.554 \Omega$$

$$R_{BL} = P_{BL} / 3I_1^2$$

$$= 9600 / 3(100)^2 = 0.32 \Omega$$

$$Z_{BL} = \frac{V_1}{I_1} = \frac{230.94}{100} = 2.3094 \Omega$$

$$X_{BL} = (Z_{BL}^2 - R_{BL}^2)^{1/2} = 2.287$$

$$X_{BL} = 2.287 + \frac{50}{25} = 4.574 \Omega = X_1 + X_2'$$

$$\text{assume } X_1 = X_2' = \frac{4.574}{2} = 2.287$$

$$\therefore 7.554 = X_1 + X_m = 2.287 + X_m$$

$$\therefore X_m = 5.526 \Omega$$

$$R_2' = R_{BL} - R_1 = 0.32 - 0.3 = 0.02 \Omega$$

$$I_2 = \frac{V_{th}}{R_{th} + \frac{R_2}{s} + jX_{th} + jX_2}$$

$$V_{th} = \frac{X_m V_1}{(R_1^2 + (X_1 + X_m)^2)^{1/2}} = 151.9 \text{ V}$$

$$R_{th} = 0.149 + 1.62j$$

$$\therefore R_{th} = 0.149, X_{th} = 1.62$$

$$I_2 =$$

Problem4: [9 marks] A three-phase 415 V, 50 Hz, 4-pole, Wye connected, induction motor. Its full load speed is 1425 r.p.m. It has the following parameters:

$R_1 = 0.25 \Omega$, $R_2' = 0.5 \Omega$, $X_1' = 0.6 \Omega$; $X_2' = 1.8 \Omega$; $X_m = 50 \Omega$. The rotational losses = 1 kW, find:

1. The line current withdrawn from the source $I_1 = \dots\dots\dots$
2. The power in air gap $P_{ag} = \dots\dots\dots 15193.86$
3. Power converted from electrical to mechanical form $P_{conv} = \dots\dots\dots 14434.17$
4. Induced torque in the motor $\tau_{ind} = \dots\dots\dots 96.77$
5. The output power of this motor $P_{out} = \dots\dots\dots 13434.17$
6. The load torque $\tau_{Load} = \dots\dots\dots$
7. Efficiency $\eta = \dots\dots\dots 85.3\%$
8. Torque and current at starting $\tau_{st} = \dots\dots\dots, I_{st} = \dots\dots\dots$

$$I_1 = \frac{V_1}{Z_1} = \frac{415/\sqrt{3}}{Z_1}$$

~~Zero Pw~~ $n_{sy} = \frac{120 (50)}{4} = 1500$, $s = 0.05$

$$\omega_{syn} = \frac{2\pi (1500)}{60} = 157$$

$$V_{th} = 236.75$$

$$Z_{th} = \frac{0.2441 + j0.5947}{R_{th} + jX_{th}} = R_{th} + jX_{th}$$

$$T_{mech} = 96.77$$

$$P_{ag} = T \cdot \omega_{sy}$$

$$1000 =$$